```
from google.colab import drive
drive.mount('/content/drive')
    Drive already mounted at /content/drive; to attempt to forcibly remount, call drive.mount("/content/drive", f
!cp /content/drive/MyDrive/FL/FLARE\ sample/tf2 net.py /content
import tf2 net
!pip install nvflare
Collecting nvflare
      Downloading nvflare-2.0.12-py3-none-any.whl (799 kB)
                                          | 799 kB 5.4 MB/s
    Collecting cryptography
      Downloading cryptography-36.0.1-cp36-abi3-manylinux 2 24 x86 64.whl (3.6 MB)
                                          | 3.6 MB 34.2 MB/s
    Requirement already satisfied: google-api-python-client in /usr/local/lib/python3.7/dist-packages (from nvfla
    Requirement already satisfied: PyYAML in /usr/local/lib/python3.7/dist-packages (from nvflare) (3.13)
    Requirement already satisfied: grpcio in /usr/local/lib/python3.7/dist-packages (from nvflare) (1.43.0)
    Requirement already satisfied: psutil in /usr/local/lib/python3.7/dist-packages (from nvflare) (5.4.8)
    Collecting tenseal == 0.3.0
      Downloading tenseal-0.3.0-cp37-cp37m-manylinux2014 x86 64.whl (4.4 MB)
                                          | 4.4 MB 31.1 MB/s
    Requirement already satisfied: numpy in /usr/local/lib/python3.7/dist-packages (from nvflare) (1.19.5)
    Requirement already satisfied: cffi>=1.12 in /usr/local/lib/python3.7/dist-packages (from cryptography->nvfla
    Requirement already satisfied: pycparser in /usr/local/lib/python3.7/dist-packages (from cffi>=1.12->cryptogr
    Requirement already satisfied: uritemplate<4dev,>=3.0.0 in /usr/local/lib/python3.7/dist-packages (from googl
    Requirement already satisfied: httplib2<1dev,>=0.15.0 in /usr/local/lib/python3.7/dist-packages (from google-
    Requirement already satisfied: google-auth<3dev,>=1.16.0 in /usr/local/lib/python3.7/dist-packages (from goog
    Requirement already satisfied: google-api-core<3dev,>=1.21.0 in /usr/local/lib/python3.7/dist-packages (from
    Requirement already satisfied: six<2dev,>=1.13.0 in /usr/local/lib/python3.7/dist-packages (from google-api-p
    Requirement already satisfied: google-auth-httplib2>=0.0.3 in /usr/local/lib/python3.7/dist-packages (from go
```

Requirement already satisfied: googleapis-common-protos<2.0dev,>=1.6.0 in /usr/local/lib/python3.7/dist-packa

```
Requirement already satisfied: setuptools>=40.3.0 in /usr/local/lib/python3.7/dist-packages (from google-api-
Requirement already satisfied: requests<3.0.0dev,>=2.18.0 in /usr/local/lib/python3.7/dist-packages (from goo
Requirement already satisfied: protobuf>=3.12.0 in /usr/local/lib/python3.7/dist-packages (from google-api-co
Requirement already satisfied: packaging>=14.3 in /usr/local/lib/python3.7/dist-packages (from google-api-cor
Requirement already satisfied: pytz in /usr/local/lib/python3.7/dist-packages (from google-api-core<3dev,>=1.
Requirement already satisfied: pyasn1-modules>=0.2.1 in /usr/local/lib/python3.7/dist-packages (from google-a
Requirement already satisfied: rsa<5,>=3.1.4 in /usr/local/lib/python3.7/dist-packages (from google-auth<3dev
Requirement already satisfied: cachetools<5.0,>=2.0.0 in /usr/local/lib/python3.7/dist-packages (from google-
Requirement already satisfied: pyparsing!=3.0.5,>=2.0.2 in /usr/local/lib/python3.7/dist-packages (from packa
Requirement already satisfied: pyasn1<0.5.0,>=0.4.6 in /usr/local/lib/python3.7/dist-packages (from pyasn1-mo
Requirement already satisfied: certifi>=2017.4.17 in /usr/local/lib/python3.7/dist-packages (from requests<3.
Requirement already satisfied: urllib3!=1.25.0,!=1.25.1,<1.26,>=1.21.1 in /usr/local/lib/python3.7/dist-packa
Requirement already satisfied: chardet<4,>=3.0.2 in /usr/local/lib/python3.7/dist-packages (from requests<3.0
Requirement already satisfied: idna<3,>=2.5 in /usr/local/lib/python3.7/dist-packages (from requests<3.0.0dev
Installing collected packages: tenseal, cryptography, nvflare
Successfully installed cryptography-36.0.1 nvflare-2.0.12 tenseal-0.3.0
```

```
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# distributed under the License is distributed on an "AS IS" BASIS,
# WITHOUT WARRANTIES OR CONDITIONS OF ANY KIND, either express or implied.
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# limitations under the License.
import tensorflow as tf
import numpy as np
from nvflare.apis.dxo import DXO, DataKind, from shareable
from nvflare.apis.fl constant import ReturnCode
from nvflare.apis.event type import EventType
from nvflare.apis.executor import Executor
from nvflare.apis.fl context import FLContext
```

```
from nvflare.apis.shareable import Shareable, make reply
from nvflare.apis.signal import Signal
from tf2 net import Net
class SimpleTrainer(Executor):
    def __init__(self, epochs_per_round):
        super().__init__()
        self.epochs_per_round = epochs_per_round
        self.train_images, self.train_labels = None, None
        self.test_images, self.test_labels = None, None
        self.model = None
    def handle_event(self, event_type: str, fl_ctx: FLContext):
       if event type == EventType.START_RUN:
            self.setup(fl ctx)
    def setup(self, fl ctx: FLContext):
        (self.train images, self.train labels), (
            self.test images,
            self.test_labels,
        ) = tf.keras.datasets.mnist.load data()
        self.train images, self.test images = (
            self.train images / 255.0,
            self.test_images / 255.0,
        )
       # simulate separate datasets for each client by dividing MNIST dataset in half
       client name = fl_ctx.get_identity_name()
       if client name == "site-1":
            self.train images = self.train images[: len(self.train images) // 2]
            self.train labels = self.train labels[: len(self.train labels) // 2]
            self.test images = self.test images[: len(self.test images) // 2]
            self.test labels = self.test labels[: len(self.test labels) // 2]
        elif client name == "site-2":
            self.train images = self.train images[len(self.train images) // 2 :]
            self.train_labels = self.train_labels[len(self.train_labels) // 2 :]
            self.test images = self.test images[len(self.test images) // 2 :]
```

```
self.test labels = self.test labels[len(self.test labels) // 2 :]
   model = Net()
   loss fn = tf.keras.losses.SparseCategoricalCrossentropy(from logits=True)
   model.compile(optimizer="adam", loss=loss fn, metrics=["accuracy"])
    = model(tf.keras.Input(shape=(28, 28)))
   self.var_list = [model.get_layer(index=index).name for index in range(len(model.get_weights()))]
    self.model = model
def execute(
    self,
   task name: str,
   shareable: Shareable,
   fl ctx: FLContext,
   abort_signal: Signal,
) -> Shareable:
    11 11 11
   This function is an extended function from the super class.
   As a supervised learning based trainer, the train function will run
   evaluate and train engines based on model weights from `shareable`.
   After finishing training, a new `Shareable` object will be submitted
   to server for aggregation.
   Args:
        task_name: dispatched task
        shareable: the `Shareable` object acheived from server.
        fl_ctx: the `FLContext` object achieved from server.
        abort_signal: if triggered, the training will be aborted.
   Returns:
        a new `Shareable` object to be submitted to server for aggregation.
    ......
   # retrieve model weights download from server's shareable
   if abort signal.triggered:
        return make reply(ReturnCode.TASK ABORTED)
   if task name != "train":
        return make reply(ReturnCode.TASK UNKNOWN)
```

```
dxo = from shareable(shareable)
        model weights = dxo.data
        # use previous round's client weights to replace excluded layers from server
       prev weights = {
            self.model.get layer(index=key).name: value for key, value in enumerate(self.model.get weights())
        }
        ordered model weights = {key: model weights.get(key) for key in prev weights}
        for key in self.var_list:
            value = ordered_model_weights.get(key)
            if np.all(value == 0):
                ordered_model_weights[key] = prev_weights[key]
        # update local model weights with received weights
        self.model.set weights(list(ordered model weights.values()))
        # adjust LR or other training time info as needed
        # such as callback in the fit function
        self.model.fit(
            self.train images,
            self.train labels,
            epochs=self.epochs per round,
            validation data=(self.test images, self.test labels),
        )
        # report updated weights in shareable
       weights = {self.model.get_layer(index=key).name: value for key, value in enumerate(self.model.get_weights(
        dxo = DXO(data_kind=DataKind.WEIGHTS, data=weights)
        self.log_info(fl_ctx, "Local epochs finished. Returning shareable")
        new_shareable = dxo.to_shareable()
        return new shareable
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```

```
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# limitations under the License.
import os
import pickle
import json
import tensorflow as tf
from nvflare.apis.event type import EventType
from nvflare.apis.fl constant import FLContextKey
from nvflare.apis.fl context import FLContext
from nvflare.app common.abstract.model import ModelLearnable
from nvflare.app common.abstract.model persistor import ModelPersistor
from tf2 net import Net
from nvflare.app common.app constant import AppConstants
from nvflare.app common.abstract.model import make model learnable
class TF2ModelPersistor(ModelPersistor):
    def __init__(self, save_name="tf2_model.pkl"):
        super().__init__()
        self.save_name = save_name
    def _initialize(self, fl_ctx: FLContext):
        # get save path from FLContext
        app root = fl ctx.get prop(FLContextKey.APP ROOT)
        env = None
        run args = fl ctx.get prop(FLContextKey.ARGS)
        if run args:
            env config file name = os.path.join(app root, run args.env)
            if os.path.exists(env config file name):
                try:
```

```
with open(env_config_file_name) as file:
                    env = json.load(file)
            except:
                self.system panic(
                    reason="error opening env config file {}".format(env config file name), fl ctx=fl ctx
                )
                return
    if env is not None:
        if env.get("APP_CKPT_DIR", None):
            fl_ctx.set_prop(AppConstants.LOG DIR, env["APP_CKPT_DIR"], private=True, sticky=True)
        if env.get("APP_CKPT") is not None:
            fl ctx.set prop(
                AppConstants.CKPT_PRELOAD_PATH,
                env["APP_CKPT"],
                private=True,
                sticky=True,
            )
   log dir = fl_ctx.get_prop(AppConstants.LOG_DIR)
   if log dir:
        self.log_dir = os.path.join(app_root, log_dir)
    else:
        self.log dir = app root
   self. pkl save path = os.path.join(self.log dir, self.save name)
    if not os.path.exists(self.log_dir):
        os.makedirs(self.log_dir)
   fl_ctx.sync_sticky()
def load_model(self, fl_ctx: FLContext) -> ModelLearnable:
    .....
        initialize and load the Model.
    Args:
        fl ctx: FLContext
    Returns:
        Model object
    11 11 11
```

```
if os.path.exists(self. pkl save path):
            self.logger.info(f"Loading server weights")
            with open(self. pkl save path, "rb") as f:
               model learnable = pickle.load(f)
       else:
            self.logger.info(f"Initializing server model")
            network = Net()
            loss_fn = tf.keras.losses.SparseCategoricalCrossentropy(from_logits=True)
            network.compile(optimizer="adam", loss=loss_fn, metrics=["accuracy"])
            = network(tf.keras.Input(shape=(28, 28)))
            var_dict = {network.get_layer(index=key).name: value for key, value in enumerate(network.get_weights())
            model learnable = make model learnable(var_dict, dict())
       return model learnable
    def handle_event(self, event: str, fl_ctx: FLContext):
       if event == EventType.START RUN:
            self._initialize(fl_ctx)
    def save model(self, model learnable: ModelLearnable, fl ctx: FLContext):
            persist the Model object
       Args:
            model: Model object
            fl ctx: FLContext
       model_learnable_info = {k: str(type(v)) for k, v in model_learnable.items()}
        self.logger.info(f"Saving aggregated server weights: \n {model_learnable_info}")
       with open(self._pkl_save_path, "wb") as f:
            pickle.dump(model_learnable, f)
!poc -n 2
    This will delete poc folder in current directory and create a new one. Is it OK to proceed? (y/N) y
    Successfully creating poc folder. Please read poc/Readme.rst for user guide.
!mkdir -p poc/admin/transfer
```

Done [1532 usecs] 2022-02-13 18:39:38.174908
> upload\_app hello-tf2
Created folder /content/poc/server/startup/../transfer/hello-tf2

```
> set_run_number 1
Created a new run folder: run_1
| CLIENT | RESPONSE |
| site-1 | OK
| site-2 | OK
Done [502768 usecs] 2022-02-13 18:43:29.389927
> deploy app hello-tf2 all
deployed app "hello-tf2" to Server
 CLIENT | RESPONSE |
 site-1 | OK
| site-2 | OK
Done [406576 usecs] 2022-02-13 18:43:48.774886
> start_app all
Server app is starting....
| CLIENT | RESPONSE |
| site-1 |
| site-2 |
Done [15383932 usecs] 2022-02-13 18:44:22.332943
> check status server
FL_app name: hello-tf2
Engine status: started
Current run number: 1
Registered clients: 2
                                             LAST CONNECT TIME
 site-1 | d2a8e53a-78a9-4e48-b8d1-83dcfc39d8be | Sun Feb 13 18:44:43 2022 |
 site-2 | 9094ec01-1dad-4fdf-92b4-7f922de61b50 | Sun Feb 13 18:44:46 2022
```

from google.colab import drive
drive.mount('/content/drive')